



Robot Offline Programming Lab

Software Specification

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| Make | : KUKA |
| Software | : SimLayout / SimPro |
| Version | : 3.0 |
| License Type | : LAN Based |

Offline programming (OLP) has been an important technological advancement for industrial robots, allowing for quicker deployment at a lower initial cost. OLP has become an essential part of planning and designing an industrial robot system to eliminate the time it takes to program a robot point by point.

OLP software is used by a wide range of manufacturers when implementing industrial robot systems, helping contribute to more productive processes. For the efficient and reliable planning of production processes we always need precise data about the type, size, reach and installation position of the components as well as reliable statements about cycle times. With the KUKA.Sim simulation software packages, we can perform accessibility analyses, prevent collisions, determine cycle times, fast commissioning or quick production changeovers and prepare the offline programming of your robots.